Feedback and Sensitivity in Climate

Alain Lahellec

12th June 2009





- 1 Motivation
 - The Basic Problem That We Studied
 - Previous Work

- 2 Our Results/Contribution
 - Main Results
 - Basic Ideas for Proofs/Implementation





- 1 Motivation
 - The Basic Problem That We Studied
 - Previous Work

- 2 Our Results/Contribution
 - Main Results
 - Basic Ideas for Proofs/Implementation





- Use itemize a lot.
- Use very short sentences or short phrases.





using the pause command:

$$\begin{cases} \partial_t \boldsymbol{\sigma_0}(t) = M^{\flat} \boldsymbol{\sigma_0}(t, 0) + |b \rangle \Upsilon(t) \\ g(t) = \langle c | \boldsymbol{\sigma_0}(t, 0) , \end{cases}$$
(1)

$$\Delta\theta(t) = \langle c(t) \mid \Phi(t,0)' \eta_0^r + \langle c \mid (t) \int_0^t \Phi(t,\tau) \mid b > (\tau) \Delta\theta_0(\tau) d\tau$$
 (2)

using overlay specifications:

with the definition of the propagator as:

$$\partial_t \Phi(t,\tau) = M(t)\Phi(t,\tau); \quad \Phi(\tau,\tau) = I,$$
 (3)



with the identity matrix /.

using the pause command:

$$\begin{cases} \partial_t \boldsymbol{\sigma_0}(t) = M^{\flat} \boldsymbol{\sigma_0}(t, 0) + |b \rangle \Upsilon(t) \\ g(t) = \langle c | \boldsymbol{\sigma_0}(t, 0), \end{cases}$$
 (1)

$$\Delta\theta(t) = \langle c(t) \mid \Phi(t,0)' \eta_0' \rangle + \langle c \mid (t) \int_0^t \Phi(t,\tau) \mid b > (\tau) \Delta\theta_0(\tau) d\tau \quad (2)$$

- using overlay specifications:
 - First item.
 - Second item.
- with the definition of the propagator as:

$$\partial_t \Phi(t,\tau) = M(t)\Phi(t,\tau); \quad \Phi(\tau,\tau) = I,$$
 (3)

with the identity matrix I.



using the pause command:

$$\begin{cases} \partial_t \boldsymbol{\sigma_0}(t) = M^{\flat} \boldsymbol{\sigma_0}(t, 0) + |b \rangle \Upsilon(t) \\ g(t) = \langle c | \boldsymbol{\sigma_0}(t, 0), \end{cases}$$
(1)

•

$$\Delta\theta(t) = \langle c(t) \mid \Phi(t,0)' \eta_0' \rangle + \langle c \mid (t) \int_0^t \Phi(t,\tau) \mid b > (\tau) \Delta\theta_0(\tau) d\tau \quad (2)$$

- using overlay specifications:
 - First item.
 - · Second item.
- with the definition of the propagator as:

$$\partial_t \Phi(t,\tau) = M(t)\Phi(t,\tau); \quad \Phi(\tau,\tau) = I,$$
 (3)

with the identity matrix *I*.



using the pause command:

$$\begin{cases}
\partial_t \boldsymbol{\sigma_0}(t) = M^b \boldsymbol{\sigma_0}(t, 0) + |b \rangle \Upsilon(t) \\
g(t) = \langle c | \boldsymbol{\sigma_0}(t, 0),
\end{cases}$$
(1)

•

$$\Delta\theta(t) = \langle c(t) \mid \Phi(t,0)' \eta_0' \rangle + \langle c \mid (t) \int_0^t \Phi(t,\tau) \mid b > (\tau) \Delta\theta_0(\tau) d\tau \quad (2)$$

- using overlay specifications:
 - First item.
 - Second item.
- with the definition of the propagator as:

$$\partial_t \Phi(t,\tau) = M(t)\Phi(t,\tau); \quad \Phi(\tau,\tau) = I,$$
 (3)



using the pause command:

$$\begin{cases}
\partial_t \boldsymbol{\sigma_0}(t) = M^b \boldsymbol{\sigma_0}(t, 0) + |b \rangle \Upsilon(t) \\
g(t) = \langle c | \boldsymbol{\sigma_0}(t, 0),
\end{cases}$$
(1)

•

$$\Delta\theta(t) = \langle c(t) \mid \Phi(t,0)' \eta_0' \rangle + \langle c \mid (t) \int_0^t \Phi(t,\tau) \mid b > (\tau) \Delta\theta_0(\tau) d\tau \quad (2)$$

- using overlay specifications:
 - First item.
 - Second item.
- with the definition of the propagator as:

$$\partial_t \Phi(t,\tau) = M(t)\Phi(t,\tau); \quad \Phi(\tau,\tau) = I,$$
 (3)



using the pause command:

$$\begin{cases}
\partial_t \boldsymbol{\sigma_0}(t) = M^b \boldsymbol{\sigma_0}(t, 0) + |b \rangle \Upsilon(t) \\
g(t) = \langle c | \boldsymbol{\sigma_0}(t, 0),
\end{cases}$$
(1)

•

$$\Delta\theta(t) = \langle c(t) \mid \Phi(t,0)' \eta_0' \rangle + \langle c \mid (t) \int_0^t \Phi(t,\tau) \mid b > (\tau) \Delta\theta_0(\tau) d\tau \quad (2)$$

- using overlay specifications:
 - First item.
 - Second item.
- with the definition of the propagator as:

$$\partial_t \Phi(t,\tau) = M(t)\Phi(t,\tau); \quad \Phi(\tau,\tau) = I,$$
 (3)

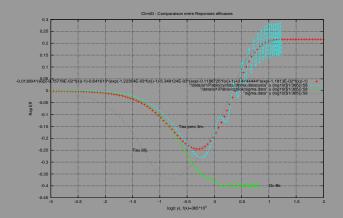


- 1 Motivation
 - The Basic Problem That We Studied
 - Previous Work

- 2 Our Results/Contribution
 - Main Results
 - Basic Ideas for Proofs/Implementation

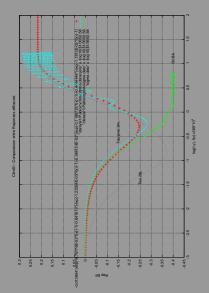








Essai avec pgfuse.







- 1 Motivation
 - The Basic Problem That We Studied
 - Previous Work

- 2 Our Results/Contribution
 - Main Results
 - Basic Ideas for Proofs/Implementation











- 1 Motivation
 - The Basic Problem That We Studied
 - Previous Work

- 2 Our Results/Contribution
 - Main Results
 - Basic Ideas for Proofs/Implementation











Summary

- The first main message of your talk in one or two lines.
- The second main message of your talk in one or two lines.
- Perhaps a third message, but not more than that.

- Outlook
 - Something you haven't solved.
 - Something else you haven't solved.





For Further Reading I



Handbook of Everything.

Some Press, 1990.

S. Someone

On this and that.

Journal of This and That, 2(1):50–100, 2000.



