

A Path-tracing Monte Carlo Library for 3D Radiative Transfer in Highly Resolved Cloudy Atmospheres

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June 28, 2019

Outline

Context: radiation in clouds, Monte Carlo

Why do we need new Monte Carlo tools?

Transferring expertise from computer graphics to atmospheric optics

Implementation and performance tests

Outlook: a parameterisation of 3D radiative effects of clouds

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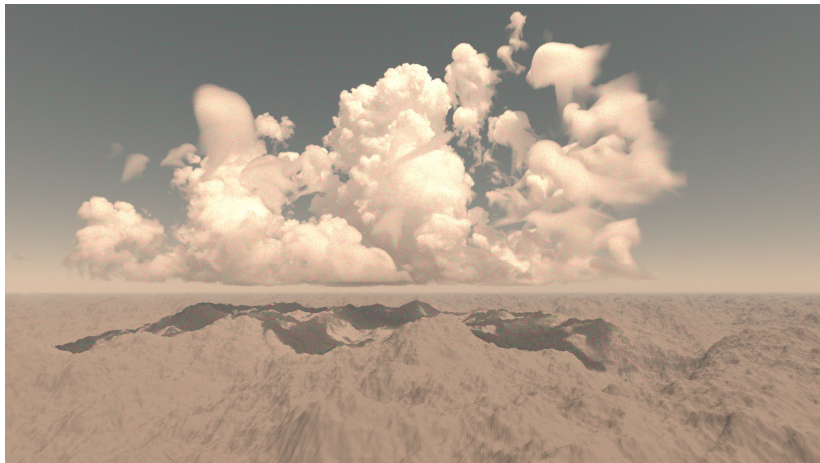
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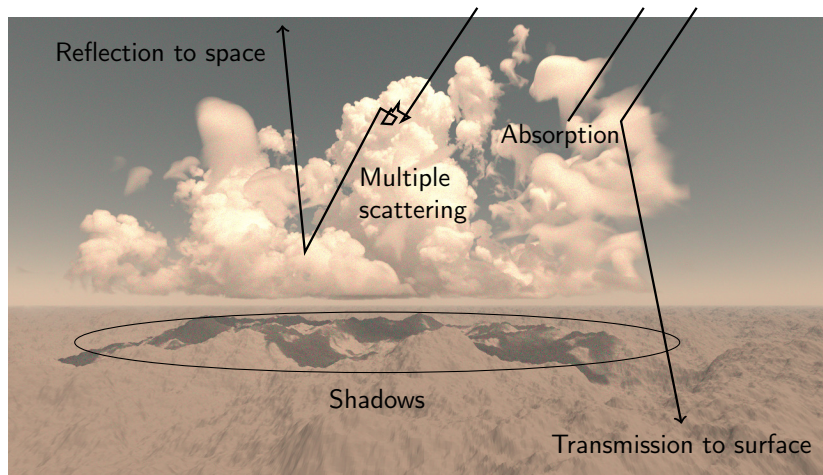
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Outlook: a parameterisation of 3D radiative effects of clouds

How do clouds affect solar radiation?

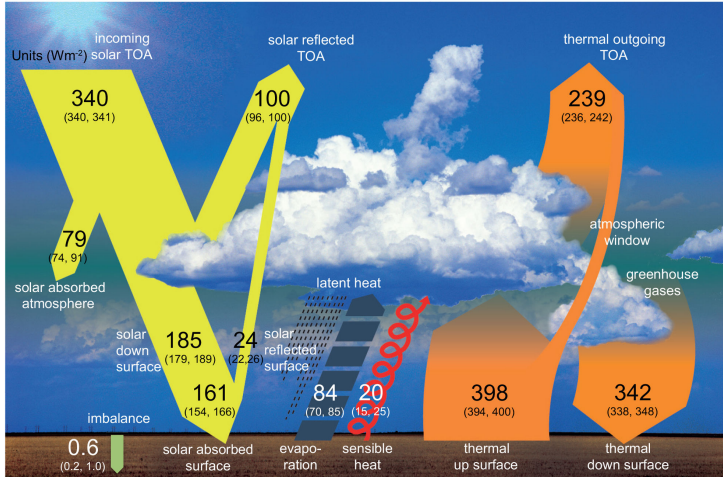


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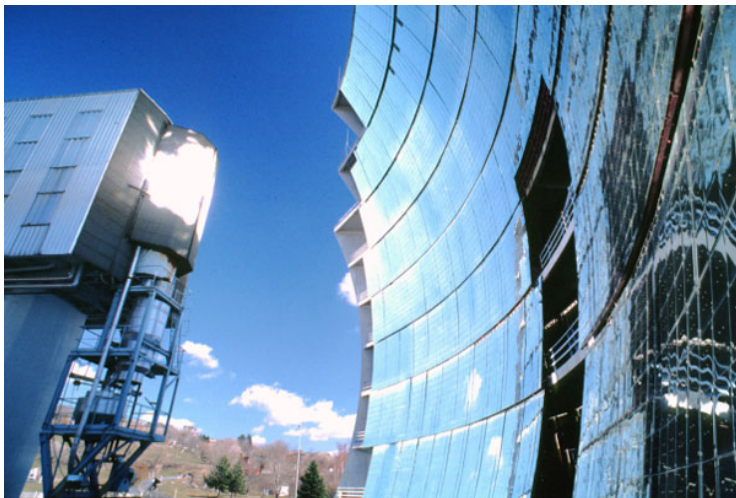
Clouds redistribute solar radiation through scattering and absorption. Scattering leads to either reflection to space or transmission to surface. Absorption heats the atmosphere. Clouds create shadows at the surface.

Why do we care about the impact of clouds on radiation?



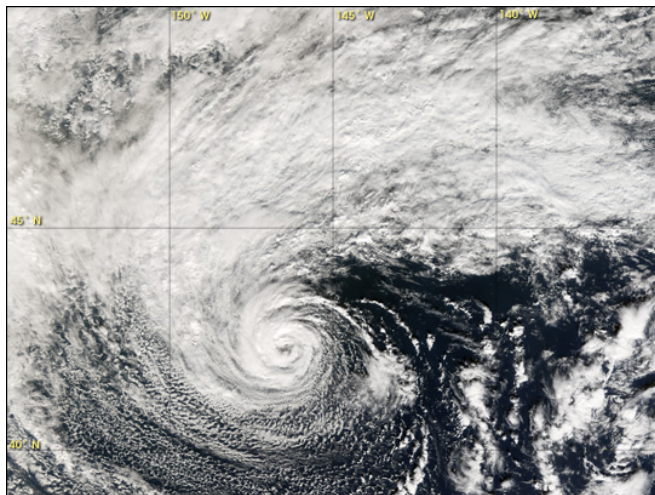
Weather & climate: understand and predict the Earth energy cycle & budget

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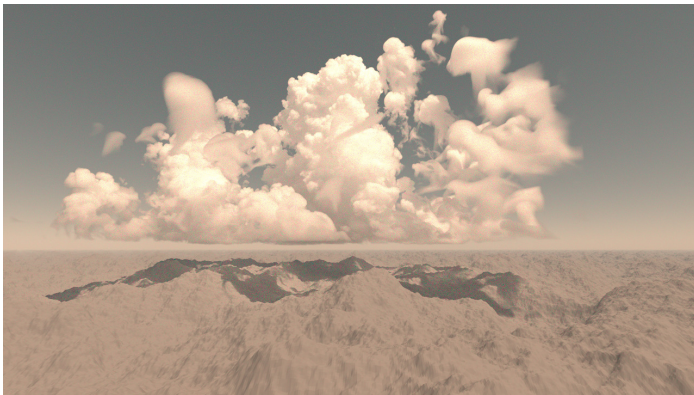
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Weather & climate: understand and predict the Earth energy cycle & budget
Solar energy: predict the amount of solar radiation that will reach a solar furnace
Atmospheric observation: use radiation observations to infer atmospheric state

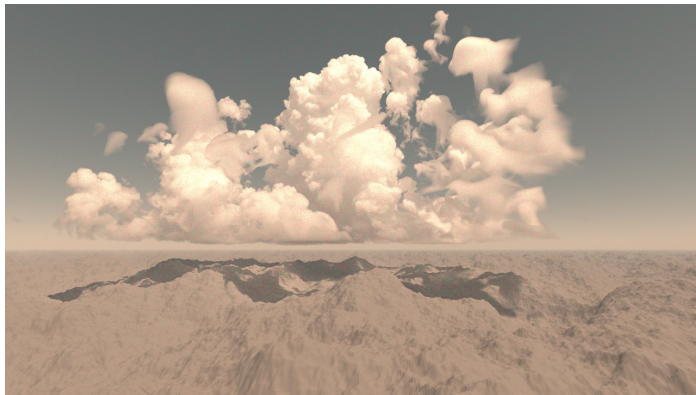
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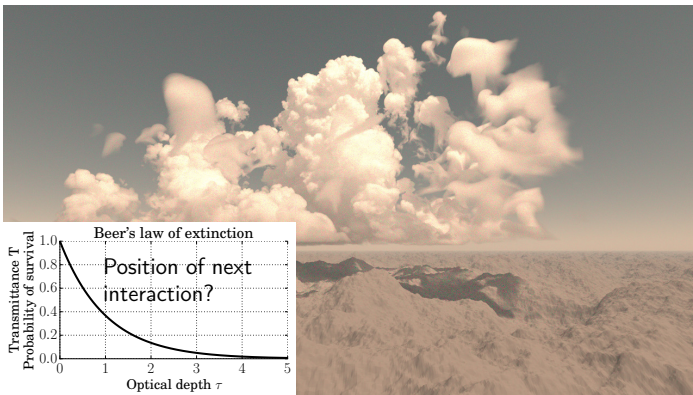
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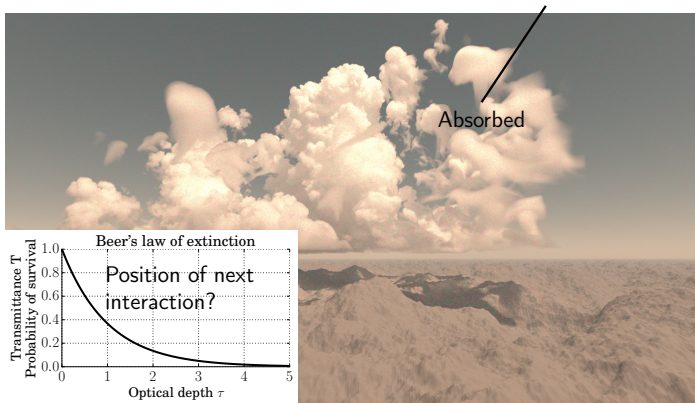
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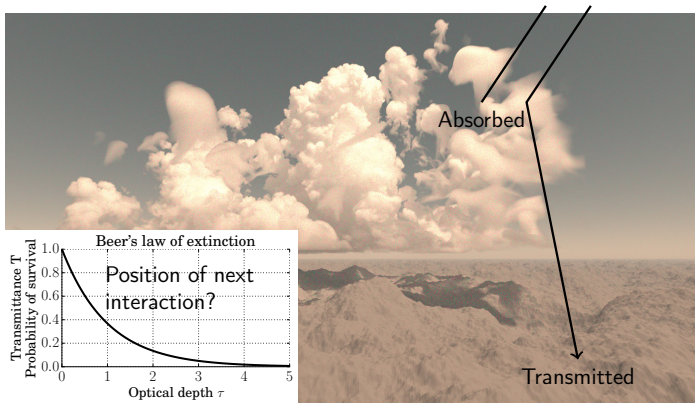
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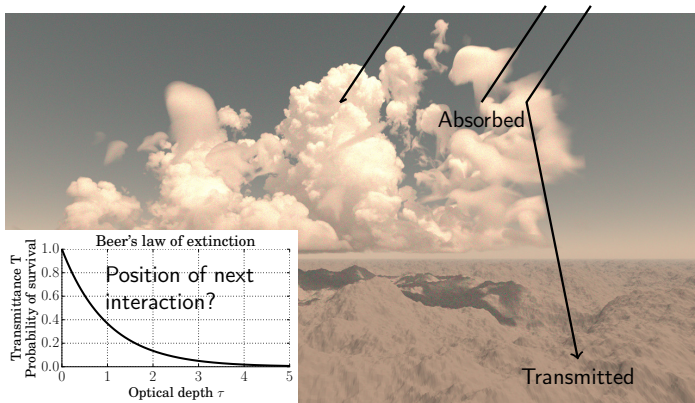
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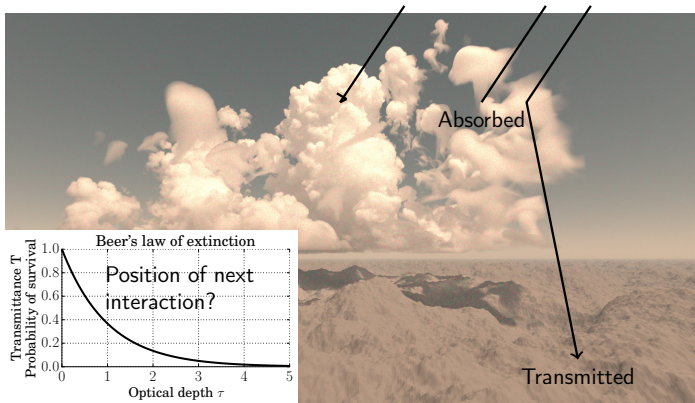
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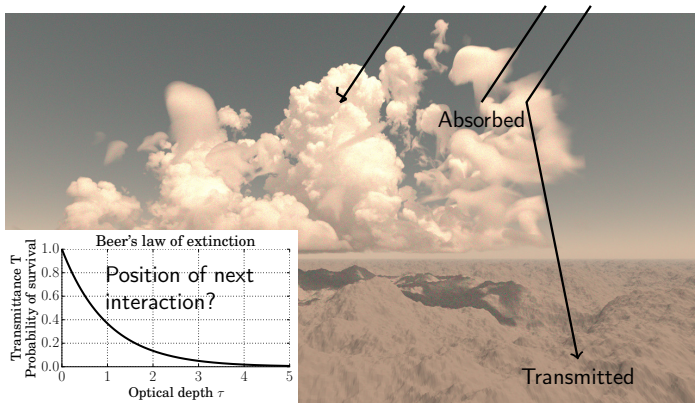
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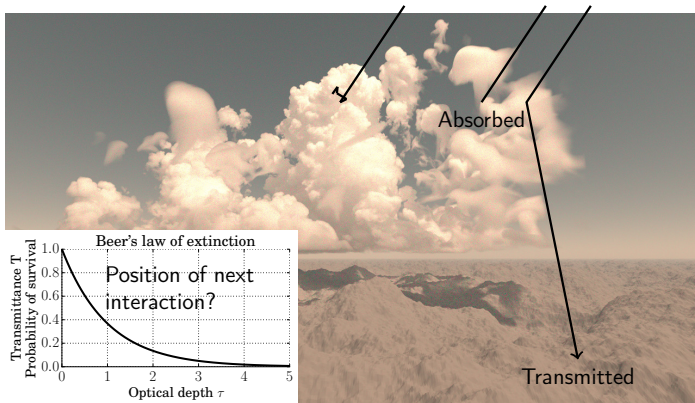
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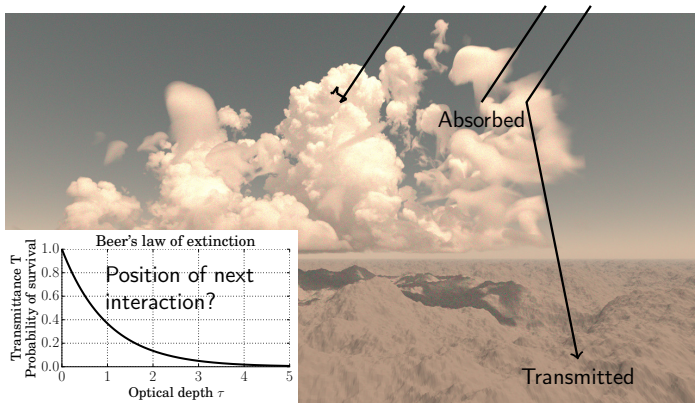
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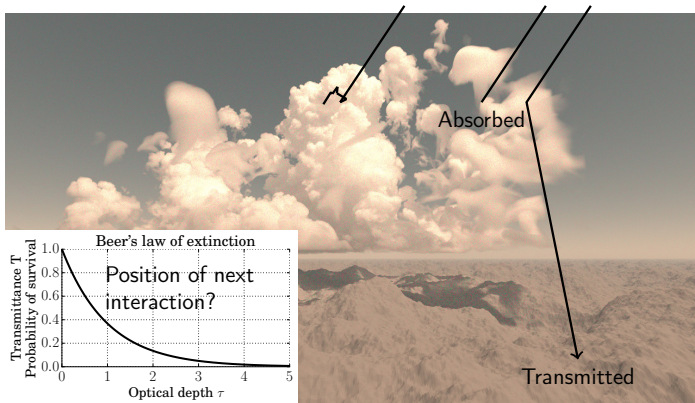
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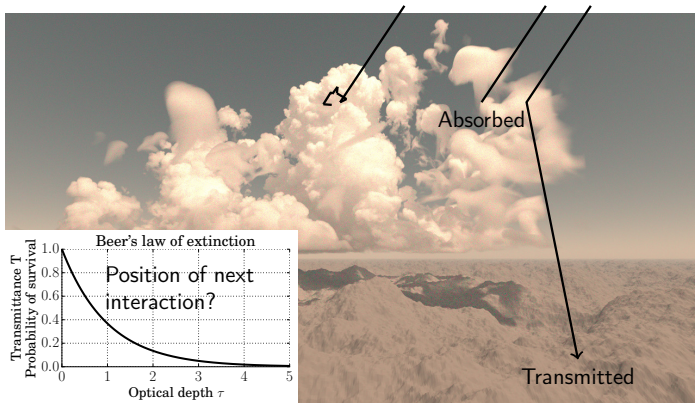
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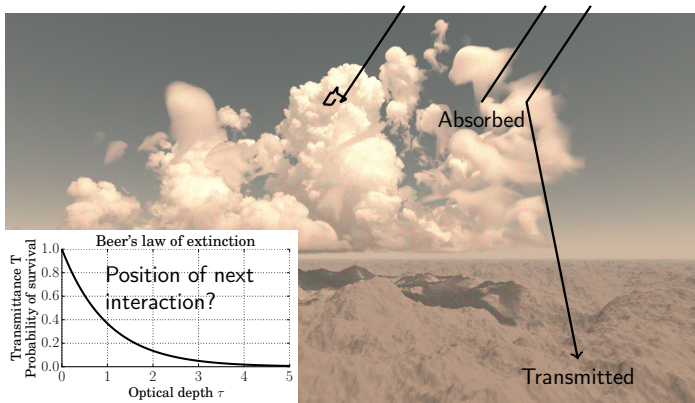
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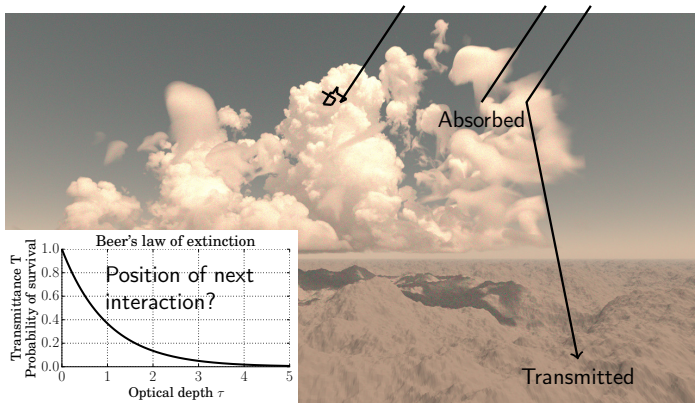
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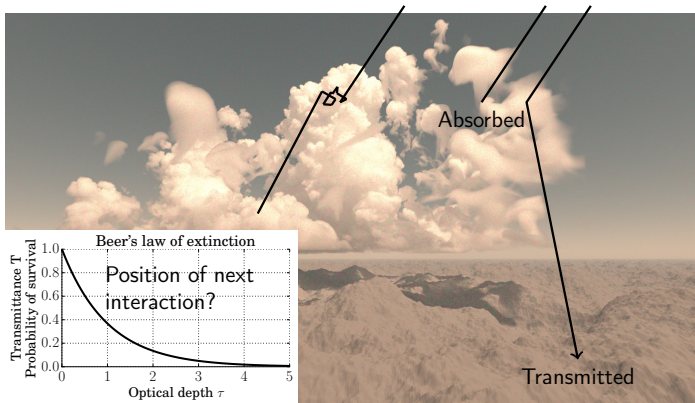
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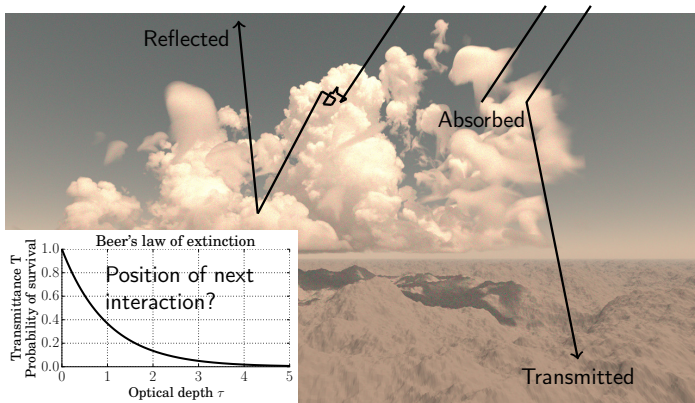
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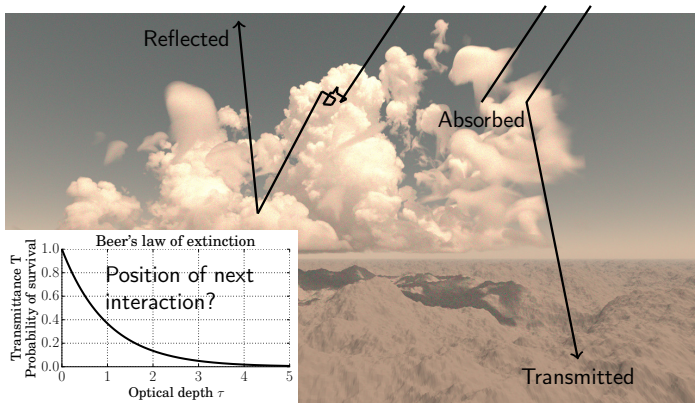
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MC methods are **accurate** and **reliable**: the distribution of sampled paths converges towards the true density of paths. Convergence rate $\sim \sqrt{N}$

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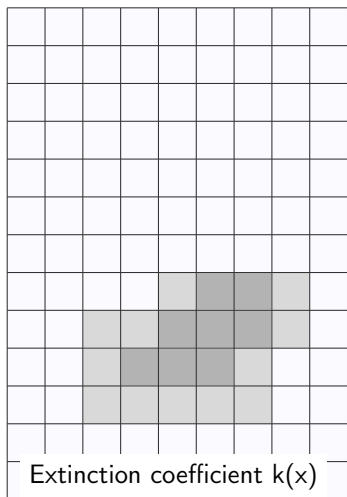
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What is going on in the existing Monte Carlo codes?

The next position of interaction depends on optical depth

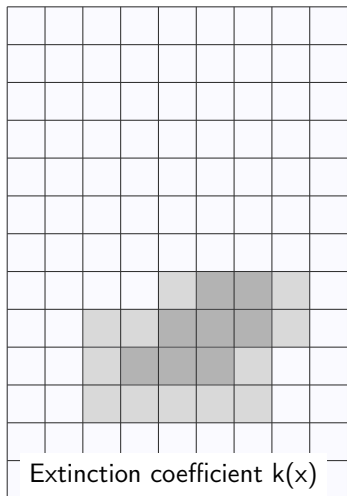
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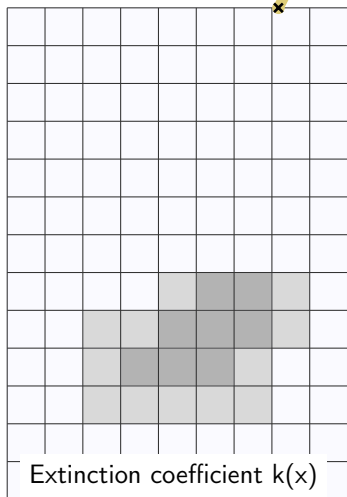
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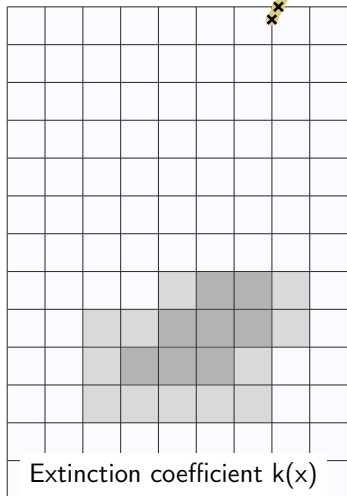
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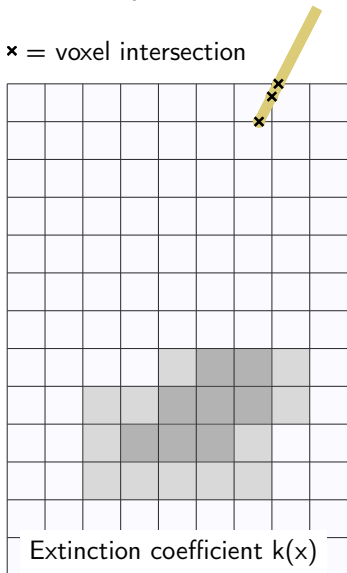
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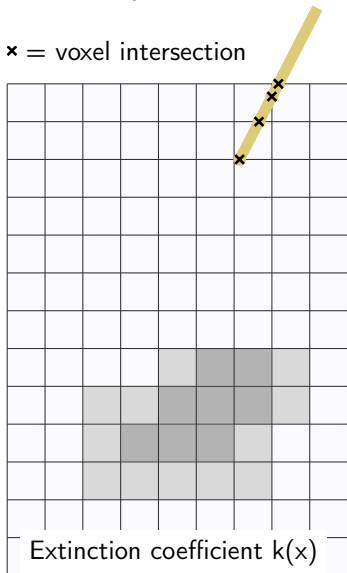
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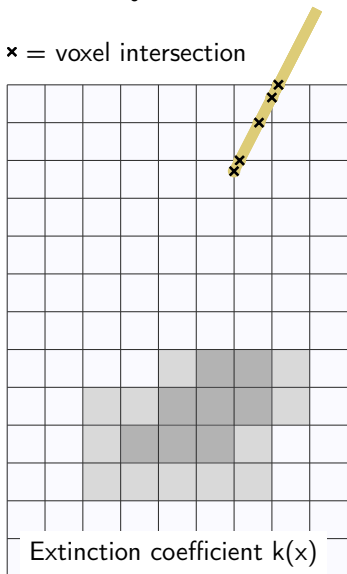
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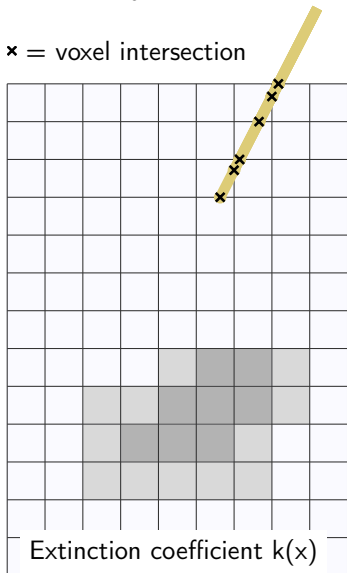
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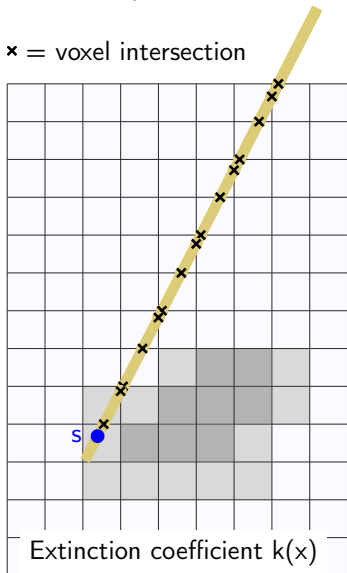
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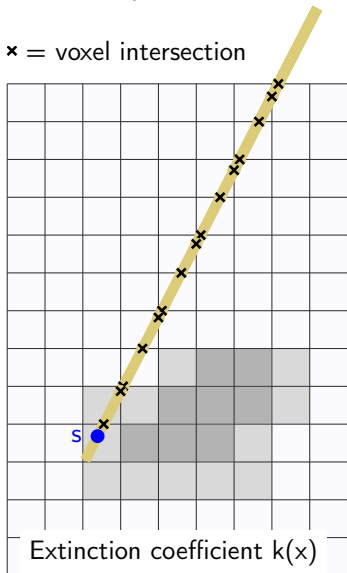
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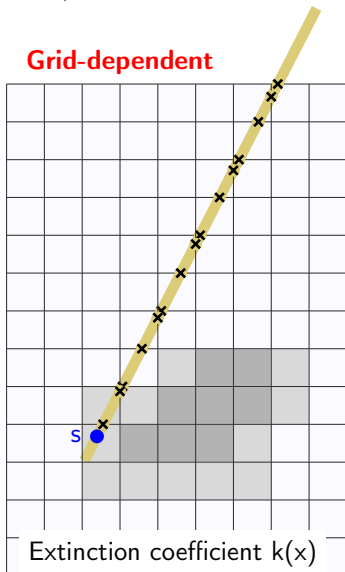
Ray tracing is grid-dependent

Computing time will ↗ with resolution

How can we avoid grid-dependent ray-tracing?

Using Null-Collision Algorithms (NCA) (Coleman, 1968; Galtier et al., 2013)
(= the Maximum Cross-Section method, Marchuk et al. (1980a))

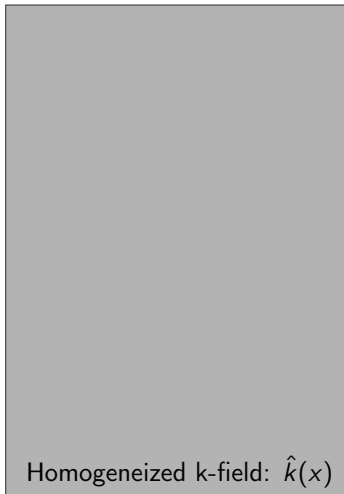
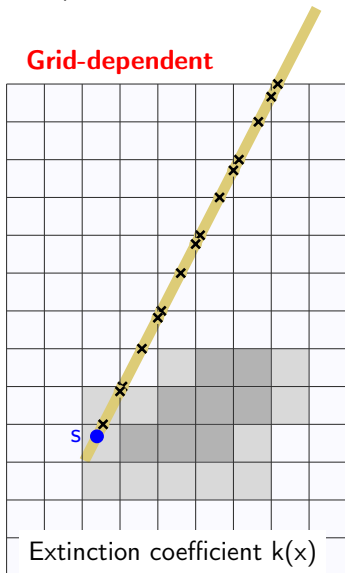
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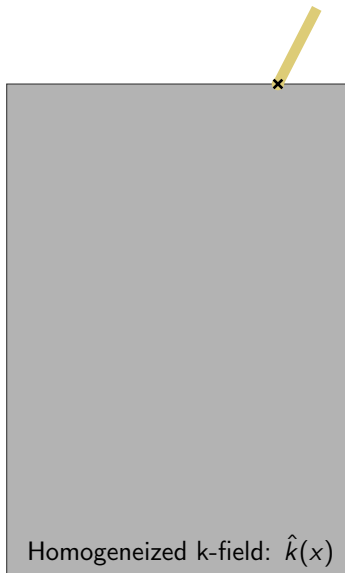
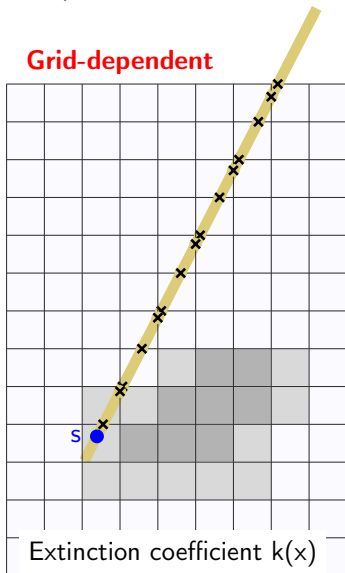
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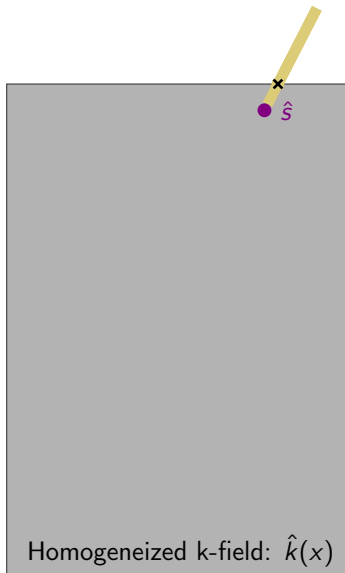
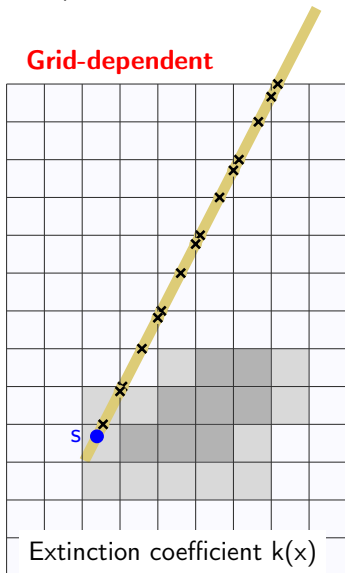
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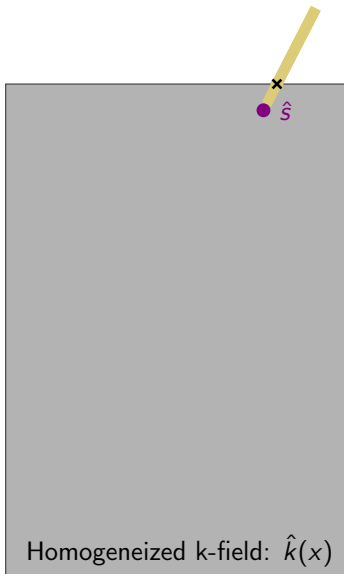
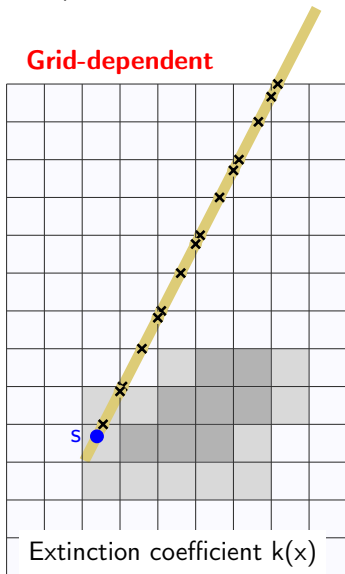
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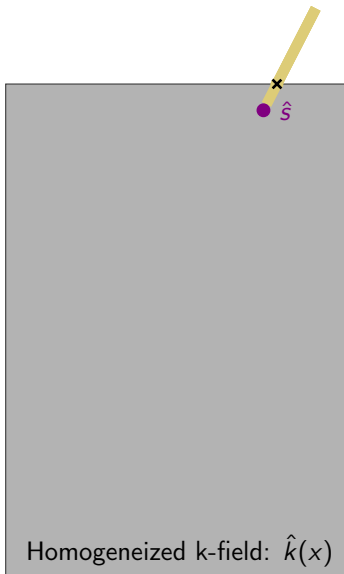
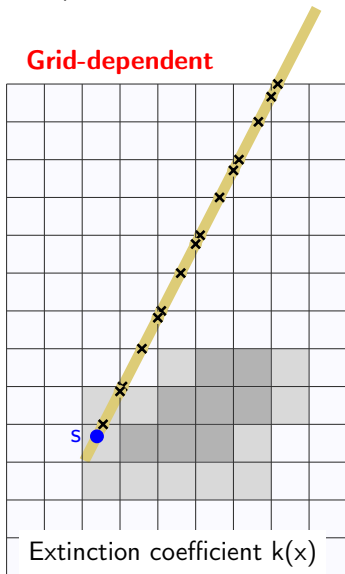
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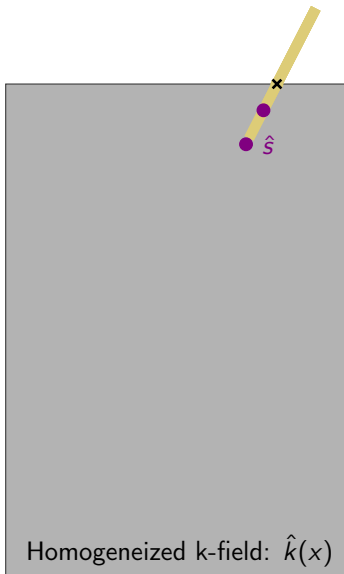
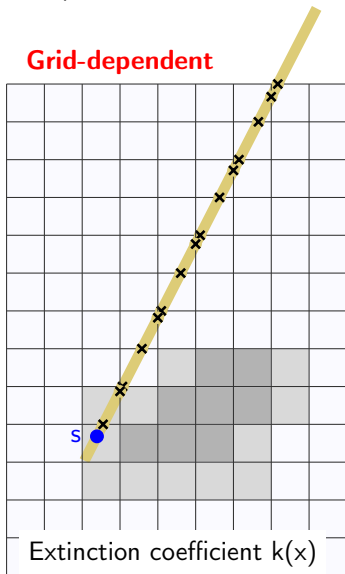
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While null: repeat

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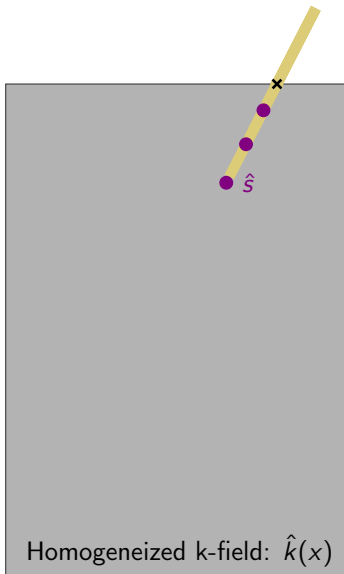
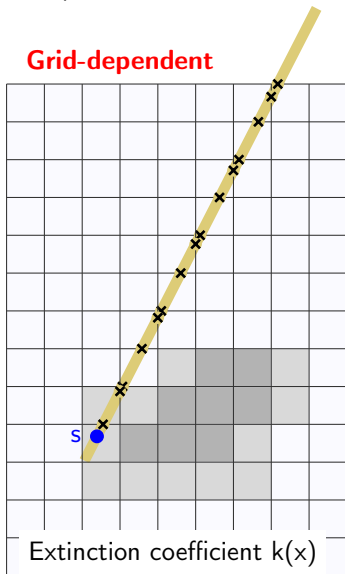
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Grid-dependent



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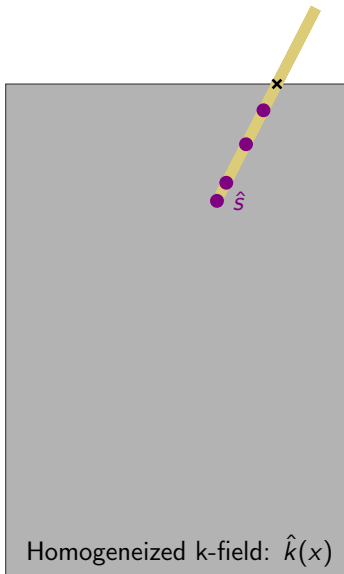
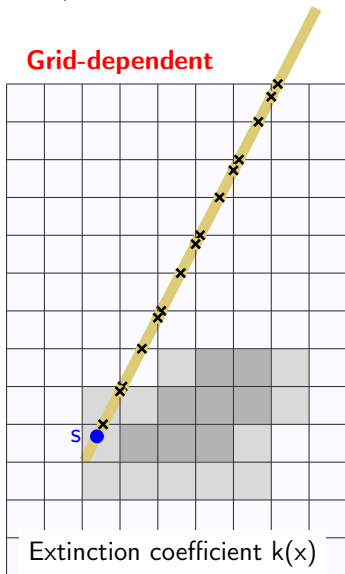
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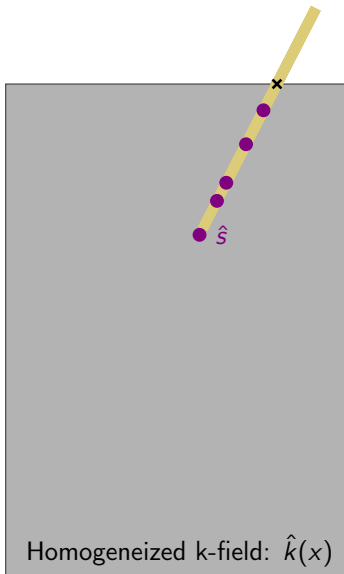
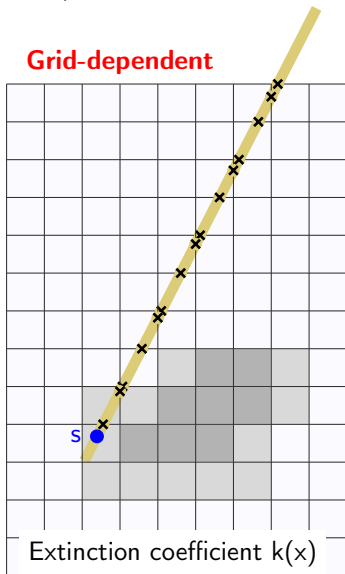
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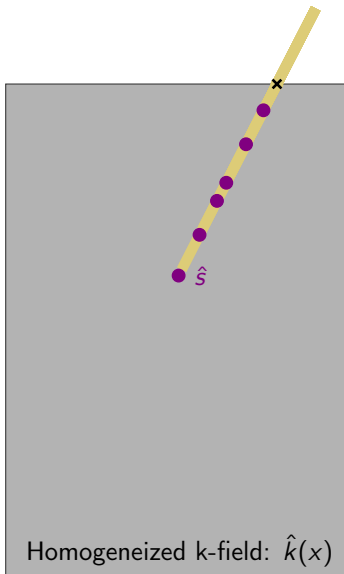
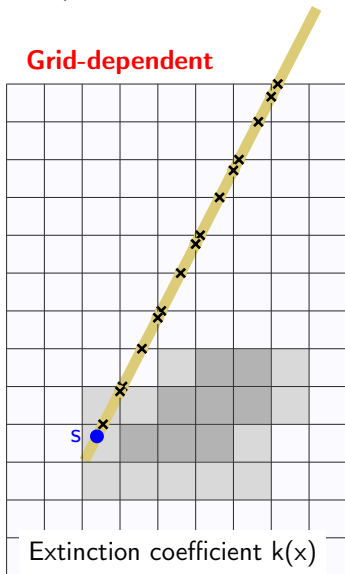
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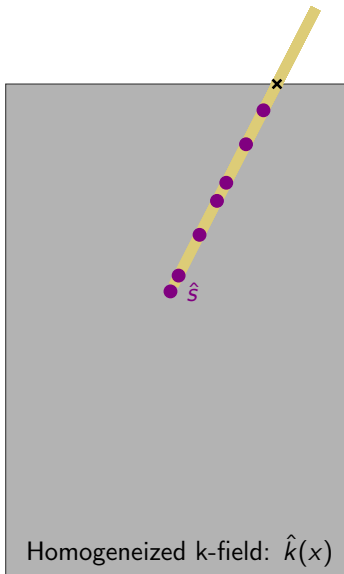
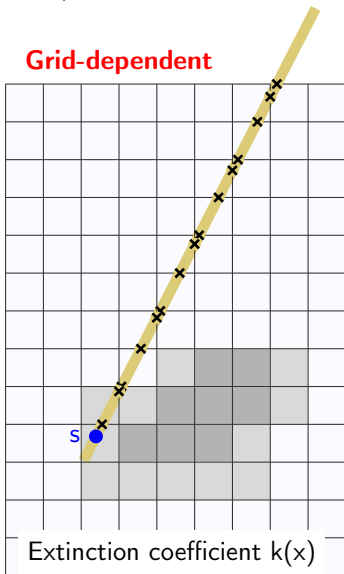
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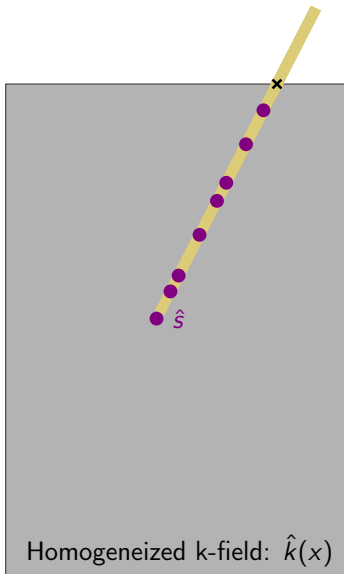
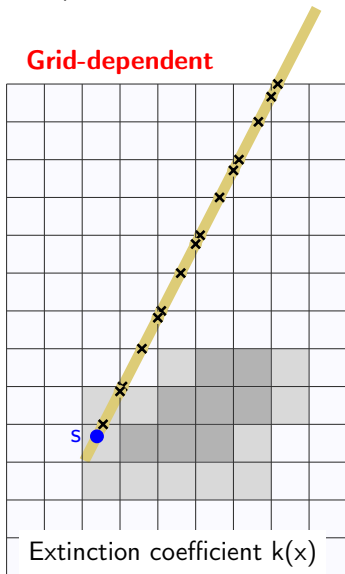
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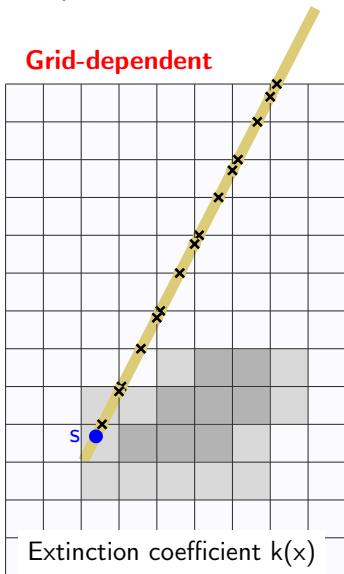
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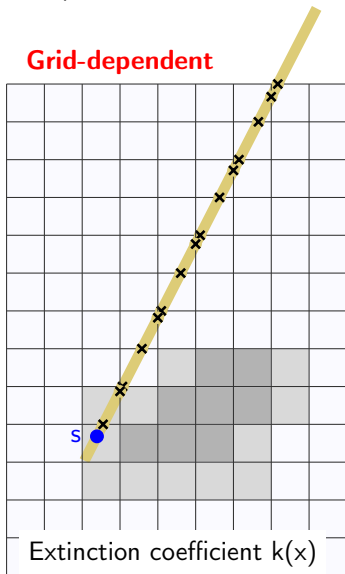
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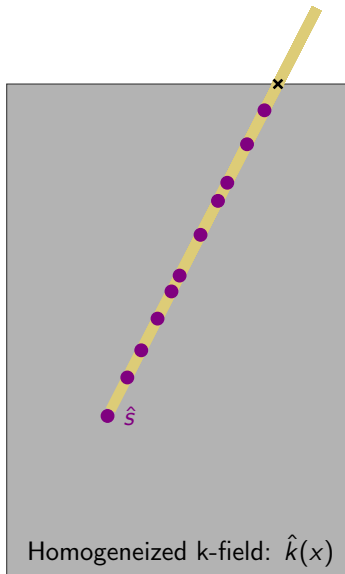
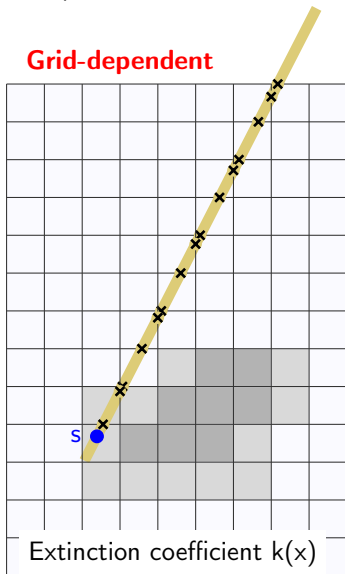
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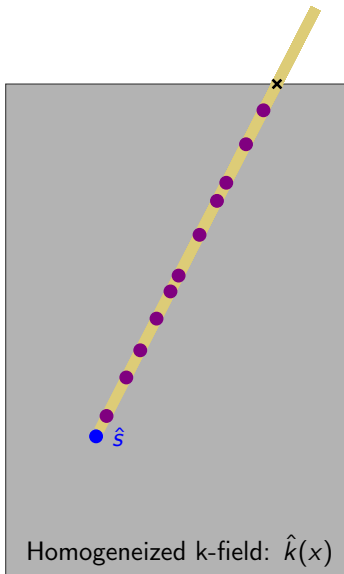
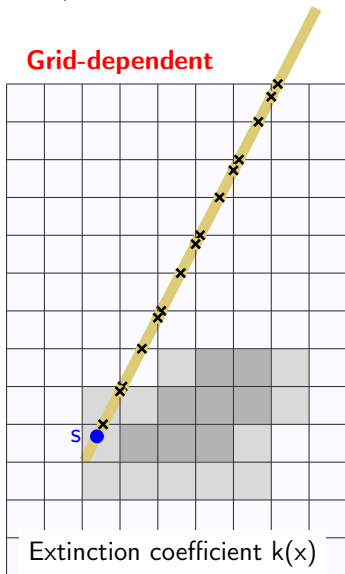
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Homogenized k-field: $\hat{k}(x)$

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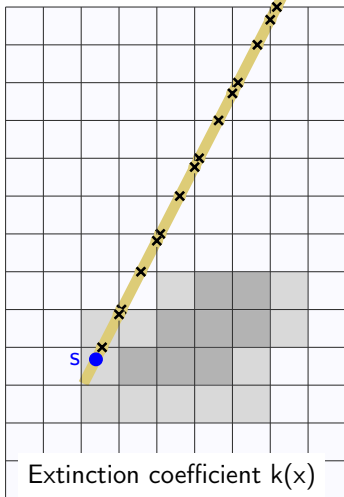
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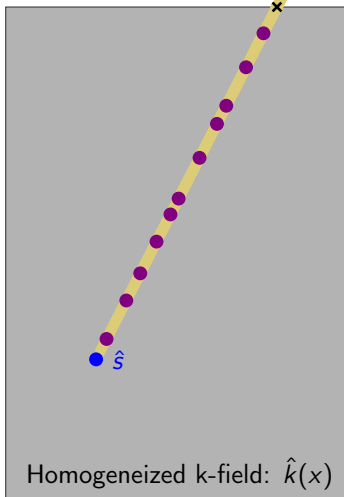
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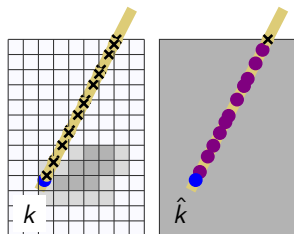
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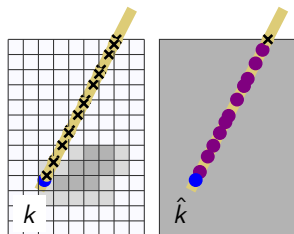
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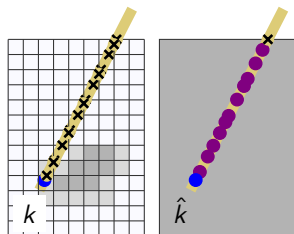
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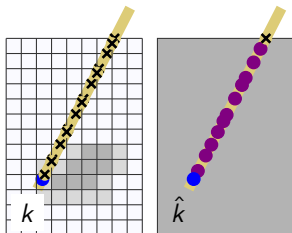
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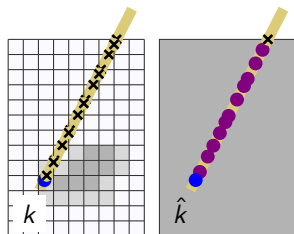
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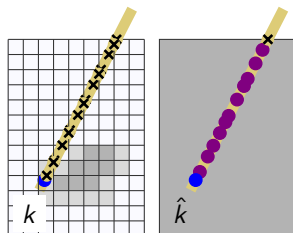
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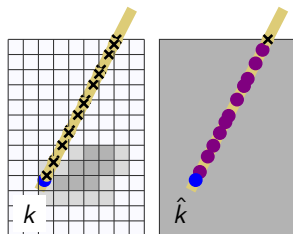
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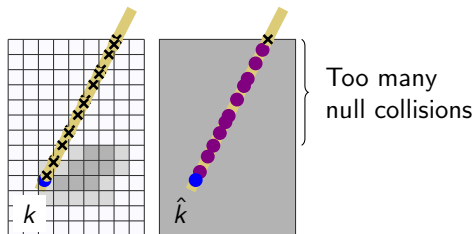
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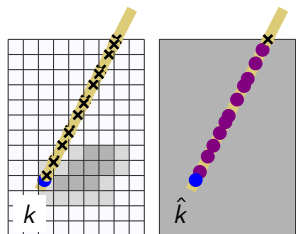
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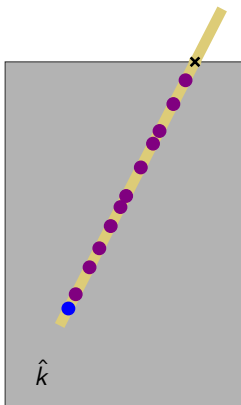
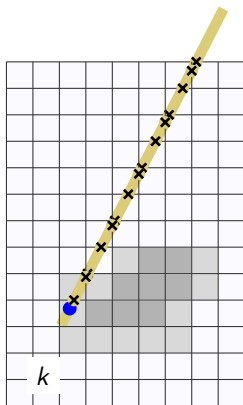


Too many
null collisions

**But who said $\hat{k}$ is
necessary uniform?**

Introducing acceleration grids for ray tracing in NCA

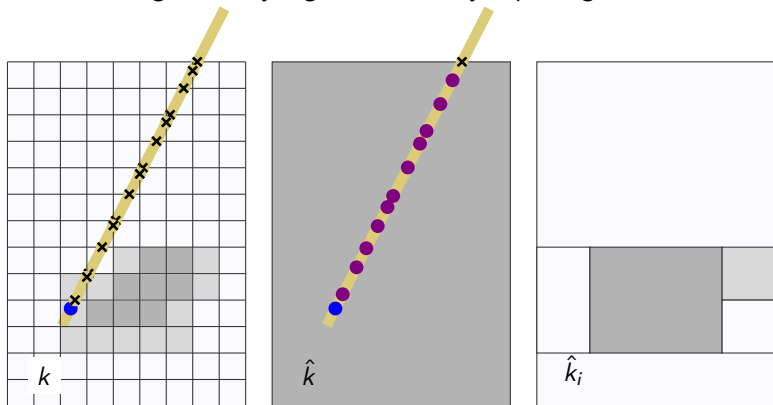
Objective: find balance between voxel intersections and null collisions



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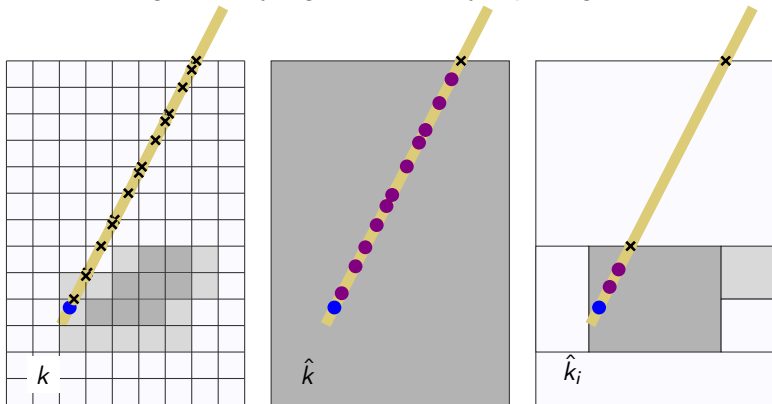
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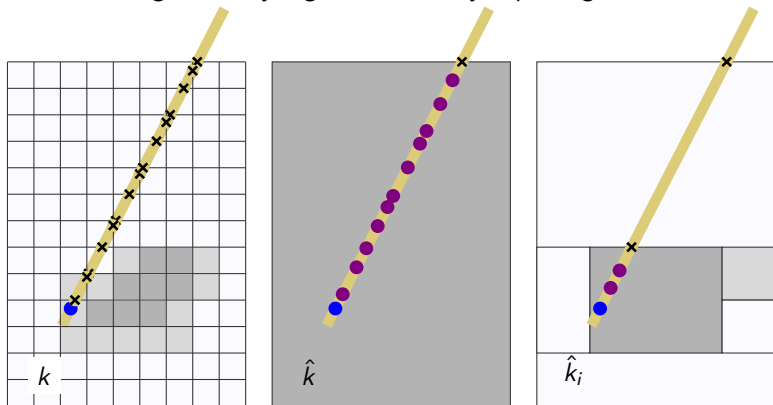
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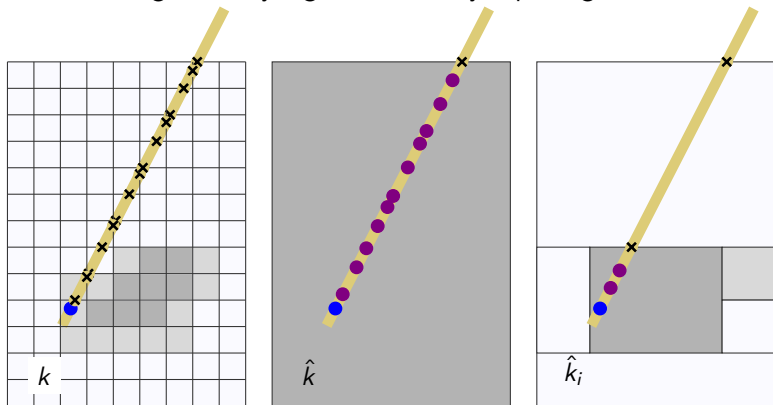


Similar idea in Iwabuchi and Okamura (2017) (refined/coarse $\hat{k}$ -grids in cloudy/clear layers).

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Similar idea in Iwabuchi and Okamura (2017) (refined/coarse $\hat{k}$ -grids in cloudy/clear layers). But outside atmospheric science, a community has been using very sophisticated grids to accelerate MC ray tracing...

The community of physically based image rendering

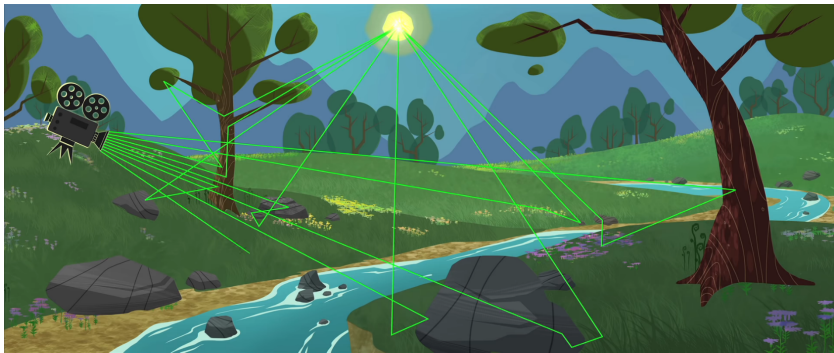
Have been using path tracing Monte Carlo to render numerical scenes made of billions of triangles (in this example 3.1 billions).



Cover of the *Physically Based Rendering* book (Pharr and Humphreys, 2018)

The community of physically based image rendering

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Disney's Practical Guide to Path Tracing (Walt Disney Animation Studios, 2016)

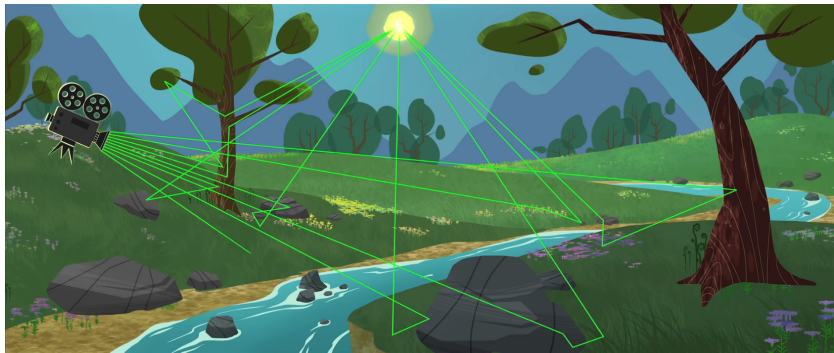
Problem: looking for next ray-surface interactions.

Testing if a given surface intersects a ray is a simple geometry problem.

Efficiently testing **billions of surfaces**... is a computer problem.

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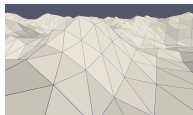
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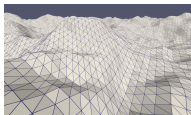
Solutions were developed: **hierarchical structures** that organize the data.

Using hierarchical structures makes rendering time insensitive to the complexity of the surface

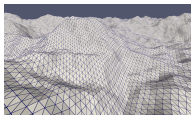
a) Ground geometries representing orography



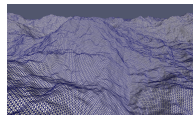
$2 \times 64 \times 64$ triangles



$2 \times 256 \times 256$ triangles



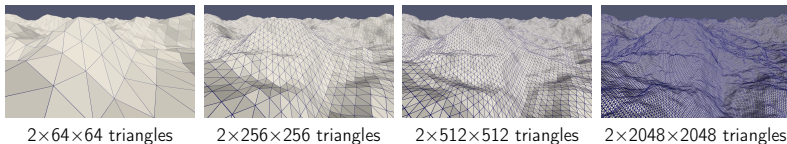
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$2 \times 2048 \times 2048$ triangles

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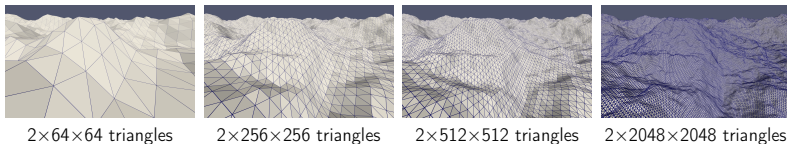


b) Relative rendering time of scenes of increasing complexity

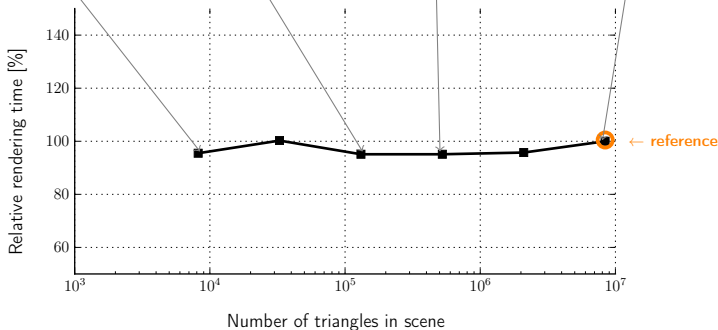


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Outline

Context: radiation in clouds, Monte Carlo

Why do we need new Monte Carlo tools?

Transferring expertise from computer graphics to atmospheric optics

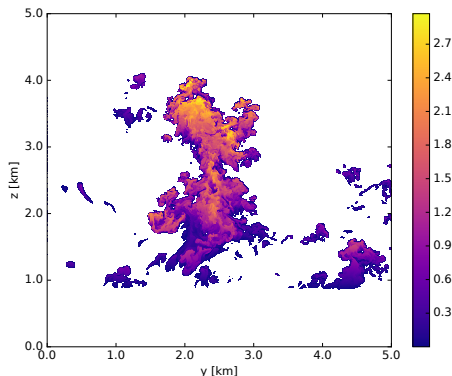
Implementation and performance tests

Outlook: a parameterisation of 3D radiative effects of clouds

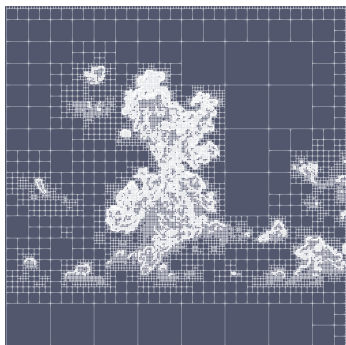
Flexible tools to implement efficient Monte Carlo codes

A collection of independent modules, distributed as a **free library**, designed for **Monte Carlo specialists**, dedicated to **fast ray-tracing** in **highly-resolved volumes** and **complex surfaces**.

a) Liquid water mixing ratio [g/kg]



b) Hierarchical grid



Hierarchical grid: recursively merged groups of voxels (until τ_i reaches $\tilde{\tau}$)
Learn more in the paper! <https://arxiv.org/abs/1902.01137> (in rev. for JAMES)

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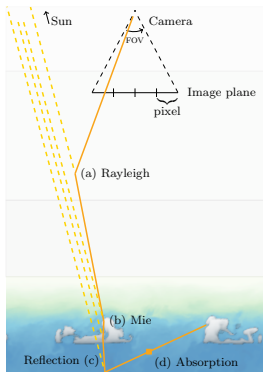
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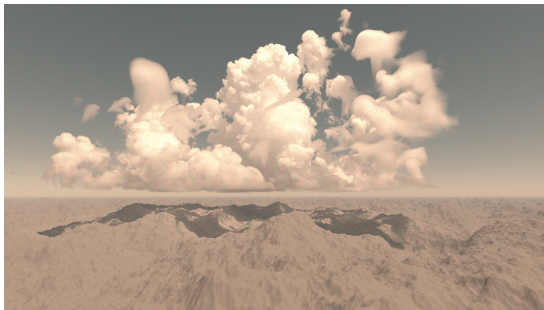
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The RenDeRer (htrdr)

A rendering application to test performances and serve as a tutorial
Computes radiance fields of 3D clouds from Large-Eddy Simulations



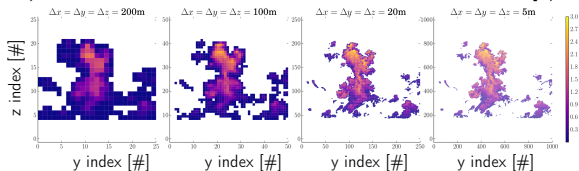
← a) Schematic illustrating the rendering algorithm



b) Example of a radiance field produced by the renderer

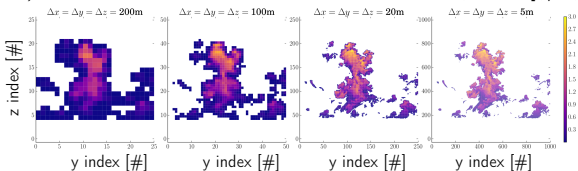
Insensitivity of computing time to resolution of cloud data

a) Vertical cross sections of liquid water mixing ratio [g/kg]

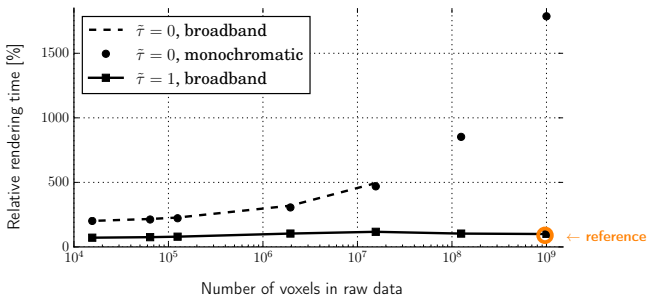


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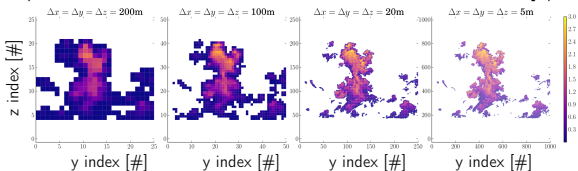
b) Relative rendering time of scenes of increasing resolution



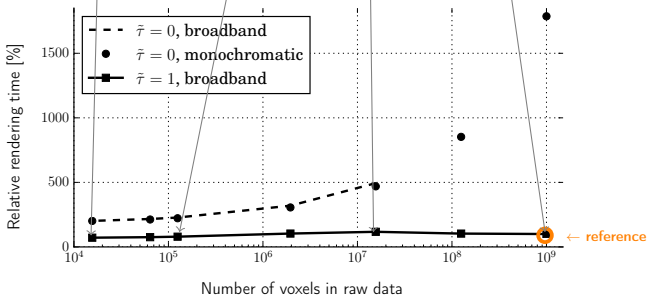
Thanks to **hierarchical grids**, rendering time is **independent** of cloud field resolution

Insensitivity of computing time to resolution of cloud data

a) Vertical cross sections of liquid water mixing ratio [g/kg]



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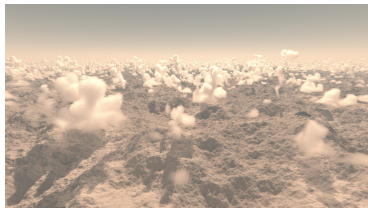


Thanks to **hierarchical grids**, rendering time is **independent** of cloud field resolution

Comparative tests for typical boundary-layer clouds (1)

Tests on marine (a) and continental (b,c) cumulus + stratocumulus (d)

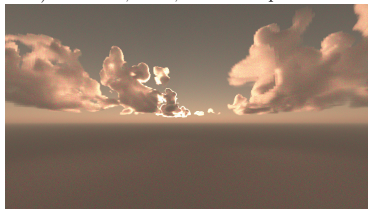
What explains difference of rendering speed? Not complexity!



a) BOMEX, 2h59, 1 054 433 paths.s⁻¹



b) ARMCu 1, 8h22, 375 983 paths.s⁻¹



c) ARMCu 2, 4h59, 631 249 paths.s⁻¹



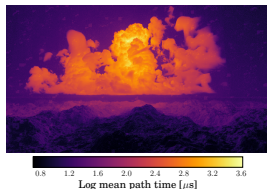
d) FIRE, 10h01, 314 049 paths.s⁻¹

$$\left(\overbrace{3}^{\text{channels}} \times \overbrace{1280 \times 720}^{\text{pixels}} \times \overbrace{4096}^{\text{paths per pixel}} \right) = 11\,324\,620\,800 \text{ paths per image}$$

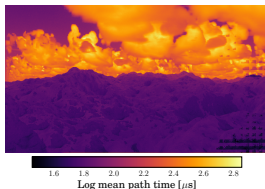
Comparative tests for typical boundary-layer clouds (2)

Mean path rendering time, averaged over pixel (map) or image ($\bar{t}$)

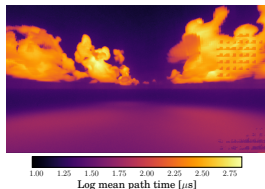
a) Congestus 5m, $\bar{t} = 110\mu s$



b) ARMCu 1, $\bar{t} = 105\mu s$



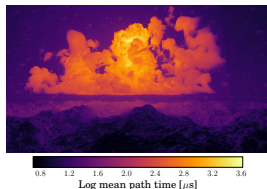
c) ARMCu 2, $\bar{t} = 60\mu s$



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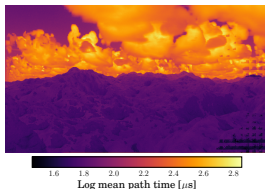
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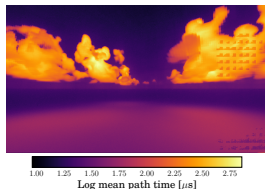
22.9% cloudy

b) ARMCu 1, $\bar{t} = 105\mu s$



39.8% cloudy

c) ARMCu 2, $\bar{t} = 60\mu s$



24.9% cloudy

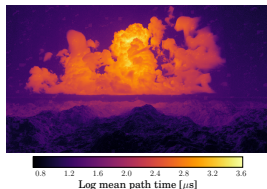
Cloud mask (black pixels): mean pixel rendering time > mean image rendering time

Strong contrast between clear & cloudy pixels,

Comparative tests for typical boundary-layer clouds (2)

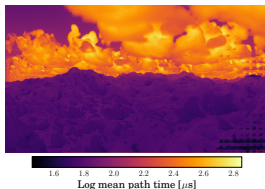
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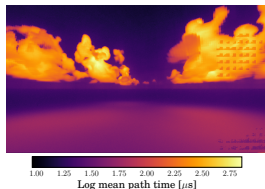
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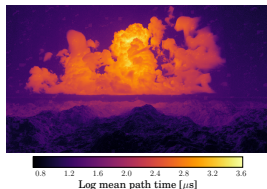
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Strong contrast between clear & cloudy pixels, thick & thin clouds

Comparative tests for typical boundary-layer clouds (2)

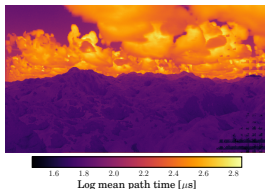
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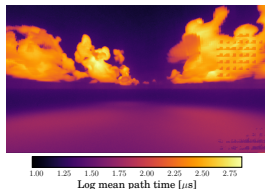
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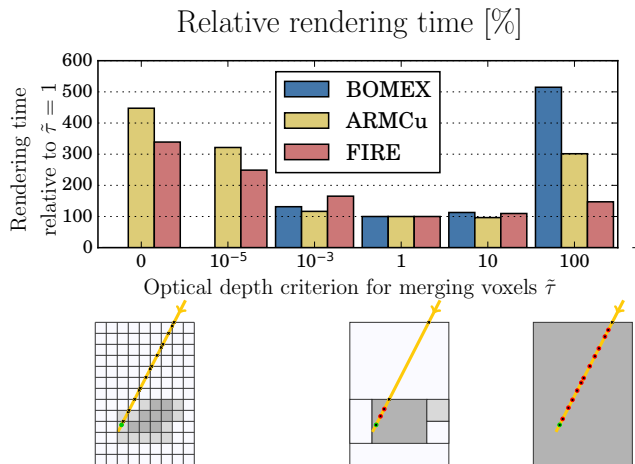


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Cloud mask (black pixels): mean pixel rendering time > mean image rendering time

Strong contrast between clear & cloudy pixels, thick & thin clouds
Path rendering time is a function of the order of scattering

Refinement of hierarchical grid



BOMEX



ARMCu



FIRE



Outline

Context: radiation in clouds, Monte Carlo

Why do we need new Monte Carlo tools?

Transferring expertise from computer graphics to atmospheric optics

Implementation and performance tests

Outlook: a parameterisation of 3D radiative effects of clouds

Cloud-radiation interactions in large-scale models

Recent developments e.g.

- ▷ cloud heterogeneity: McICA (Cahalan et al., 1994; Pincus et al., 2003); Tripleclouds (Shonk and Hogan, 2008)
- ▷ horizontal transport: SPARTACUS (Hogan and Shonk, 2013; Schäfer et al., 2016; Hogan et al., 2016)

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Mechanism	Net surface
Add horizontal structure	+3.8 (± 2)
Add 3D effects	+2.1

← adapted from Hogan (2018)
Global effect of adding complexity to radiative scheme

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Questions remain:

- ▷ Evaluate more complete diagnosis e.g. direct / diffuse partitioning
- ▷ How best to constrain cloud parameters in radiative scheme?
Parameterisations to convey available info from host model?
Tuning strategies?

Evaluation of a large-scale radiative scheme

Direct / diffuse partition important to e.g. solar energy, vegetation.

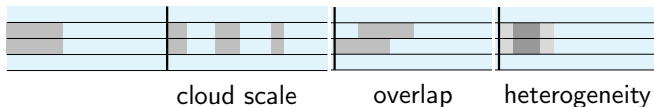
Domain-average broadband direct-to-total ground flux, MC vs ecRad.

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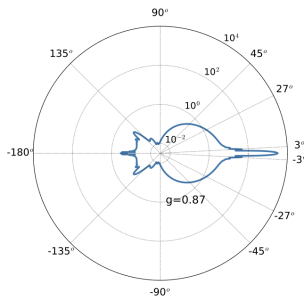
- ecRad solvers: TripleClouds (2-stream) or SPARTACUS (+ param 3D)
- Cloud characteristics diagnosed in LES field and given to ecRad.
- Overlap needs to be scaled otherwise cloud cover is overestimated.



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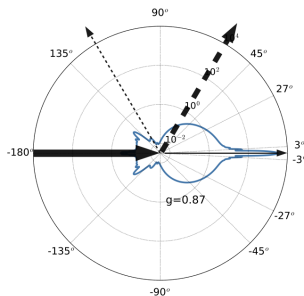


Mie phase function

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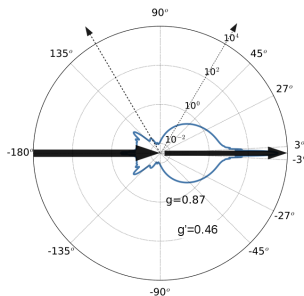


2-stream approximation (– direct, - - diffuse)

Evaluation of a large-scale radiative scheme

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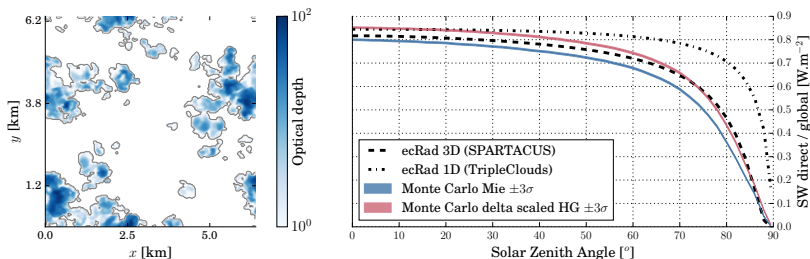
Delta-scaled 2-stream (– direct, - - diffuse) (?)

Evaluation of a large-scale radiative scheme

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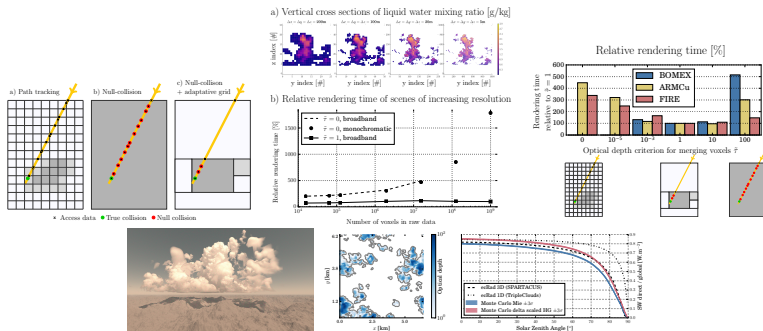
MC Mie vs MC delta-scaled HG vs SPARTACUS (- -) vs TripleClouds (-.)



Subgrid horizontal transport crucial for direct / diffuse (side illumination)

Summary

- ▶ ACN + hierarchical grids = computing time $\ll$ to data complexity
- ▶ Online distributed library to facilitate MC implementation
- ▶ Renderer to test performances, optimum hierarchical grid with $\tilde{\tau} \approx 1$
- ▶ Reference MC to study 3D effects
 - ▶ 3D effects crucial for direct / diffuse
 - ▶ SPARTACUS + cloud description from LES = close to MC



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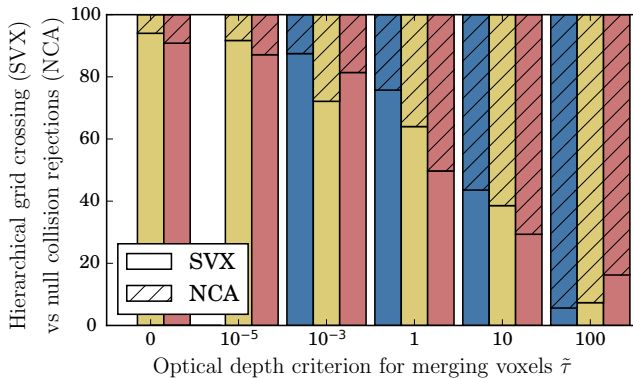
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Other results

- ▷ Refinement of hierarchical grid
- ▷ HIGH-TUNE paradigm
- ▷ Horizontal Distances for Entrapment
- ▷ Direct diffuse Monte Carlo
- ▷ Absorptivity bias in ICA MC
- ▷ Transmissivity vs reflectivity bias in ICA MC
- ▷ Direct vs diffuse surface bias in ICA MC
- ▷ Integrated ICA error and role of cloud size

Refinement of hierarchical grid ◁

Cumulative partition of costs [%]



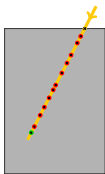
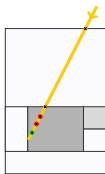
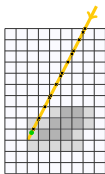
BOMEX



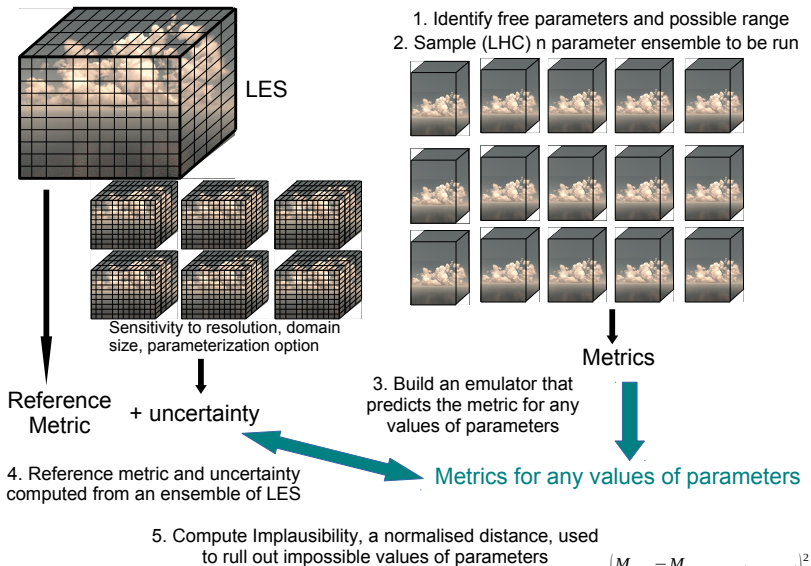
ARMCu



FIRE

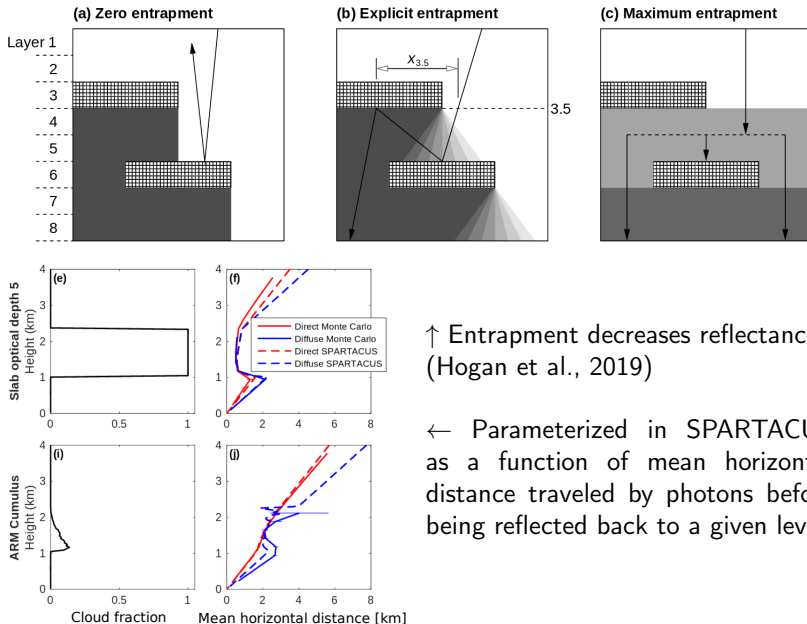


HIGH-TUNE paradigm ◁



$$I = \frac{(M_{LES} - M_{Emulator=f(p_1, \dots, p_n)})^2}{\varepsilon_{LES}^2 + \varepsilon_{Structural}^2 + \varepsilon_{Emulator}^2}$$

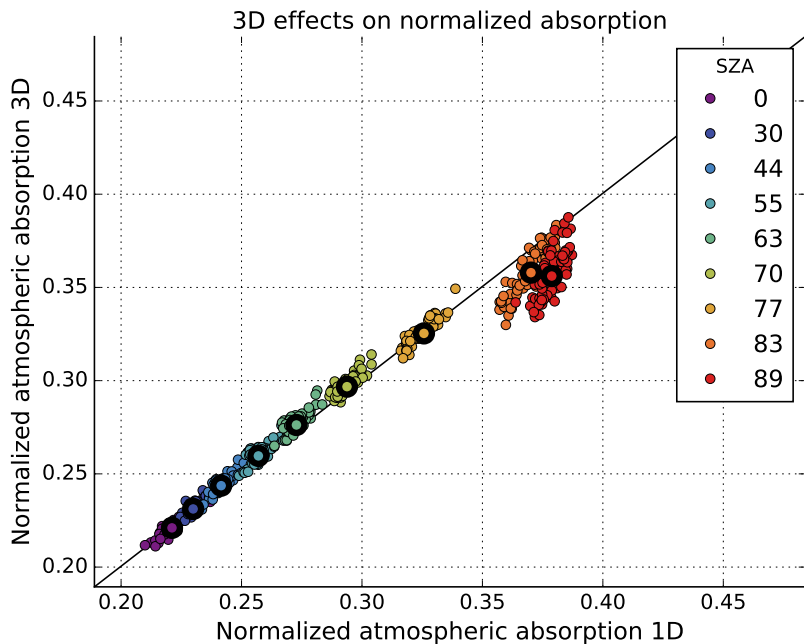
Horizontal Distances for Entrapment ◁



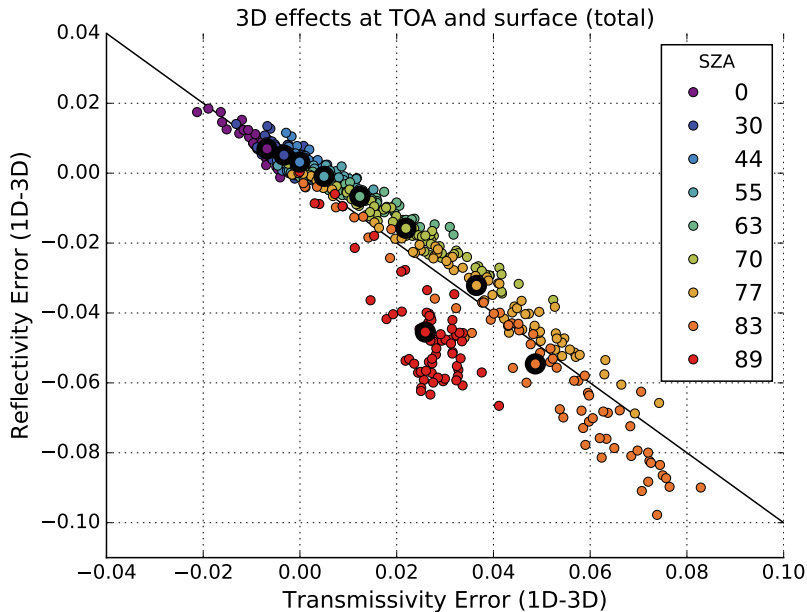
↑ Entrapment decreases reflectance
(Hogan et al., 2019)

← Parameterized in SPARTACUS
as a function of mean horizontal
distance traveled by photons before
being reflected back to a given level

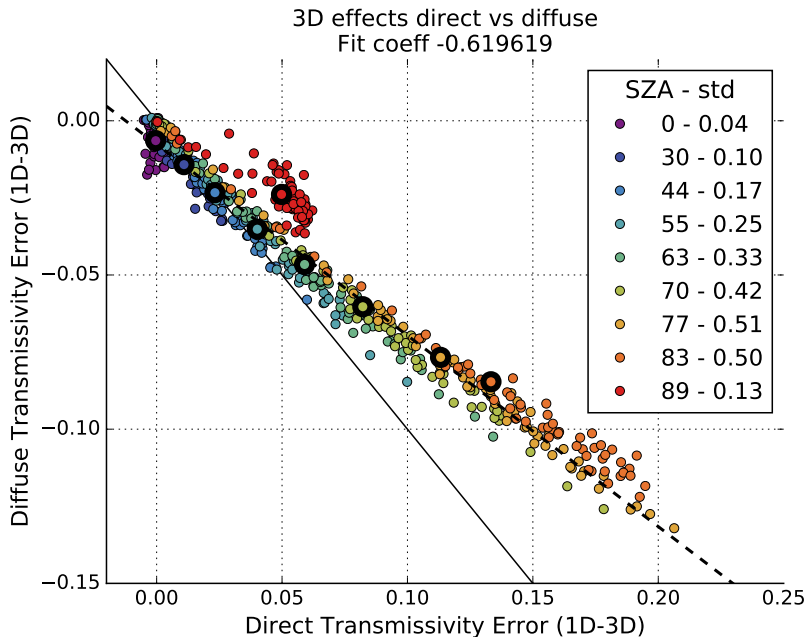
Absorptivity bias in ICA MC ◀



Transmissivity vs reflectivity bias in ICA MC ◀



Direct vs diffuse surface bias in ICA MC ◀



Integrated ICA error and role of cloud size ◀

